

**Nirma University**  
**School of Technology, Institute of Technology**  
**B. Tech (Electronics and Communication Engineering)**  
**Semester IV**

<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
2	0	2	3
<b>Course Code</b>	<b>2IC421</b>		
<b>Course Title</b>	<b>Control Systems</b>		

**Course Learning Outcomes (CLO):**

After successful completion of the course, student will be able to

- interpret and analyze stability and feedback characteristics of liner control system
- develop an ability to analyze time response of control system
- infer and simulate frequency response of control system
- illustrate basics of state space for linear time-invariant control system

**Syllabus :**

**Teaching  
hours :**

**UNIT 1: Introduction to control systems**

Introduction to linear control, open loop and closed loop control system.

**01**

**UNIT 2: Nonlinear control system**

Introduction to nonlinear control, basics of physical nonlinearities, basic control system components.

**02**

**UNIT 3: Transfer function of physical system**

Introduction and determination of transfer function, systems analogy, block diagram representation, signal flow graph.

**04**

**UNIT 4: Feedback characteristics and stability of control system**

Feedback and non-feedback systems, Sensitivity of the control system, Control of disturbance by use of feedback, Necessary condition for stability, R-H criterion.

**04**

**UNIT 5: Time domain analysis**

Typical test signals, Time response of first order system, Time response specifications, Steady state error and error constants.

**05**

**UNIT 6: Root locus analysis**

Construction of root locus, steps to solve the problem on root locus, stability analysis of control system using root locus plots.

**05**

**UNIT 7: Frequency response analysis**

Introduction to bode diagrams, construction of bode plots, nyquist plots, nyquist stability criterion, relative stability using frequency response analysis. **06**

**UNIT 8: State variable analysis**

Concept of state, state variable and state model, State space representation, solution of state equation, Derivation of transfer function from state model. **03**

**Self Study:**

The self study contents will be declared at the commencement of semester. Around 10% of the questions will be asked from self study contents.

**Laboratory Work:**

Laboratory work will consist of minimum 12 experiments based on the above syllabus.

**Suggested Readings :**

1. U.A. Patel, Control System Engineering, Mahajan Publication.
2. Nagrath & Gopal, Control System Engineering, New Age International Publication.
3. M.Gopal, Modern Control System Theory, New Age International Publication.
4. Noman S. Nise, Control System Engineering, Wiley Publication.

L= Lecture, T= Tutorial, P= Practical, C= Credit